

# Use of Lowrance HDS sonar units on Lakes Mead and Mohave for high-resolution bathymetric mapping



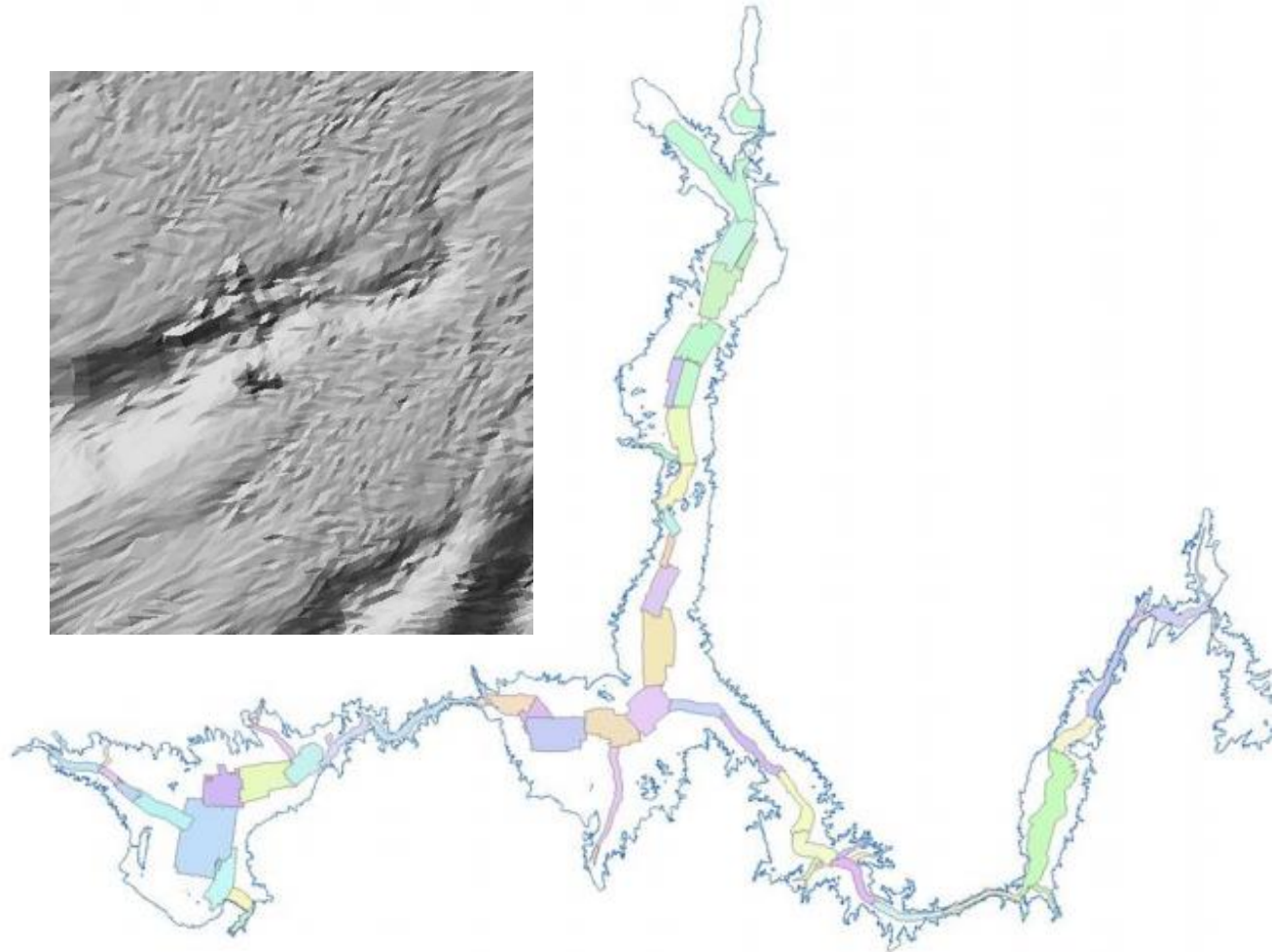
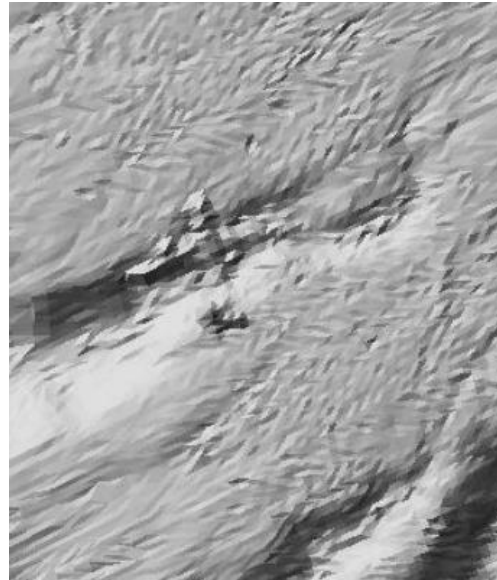
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Ben Smith, Theresa Thom and Tom Culler\*  
**National Park Service, Lake Mead NRA**



# High Resolution Bathymetric Mapping in Lake Mead

US Bureau of Reclamation  
2001 Sediment Study

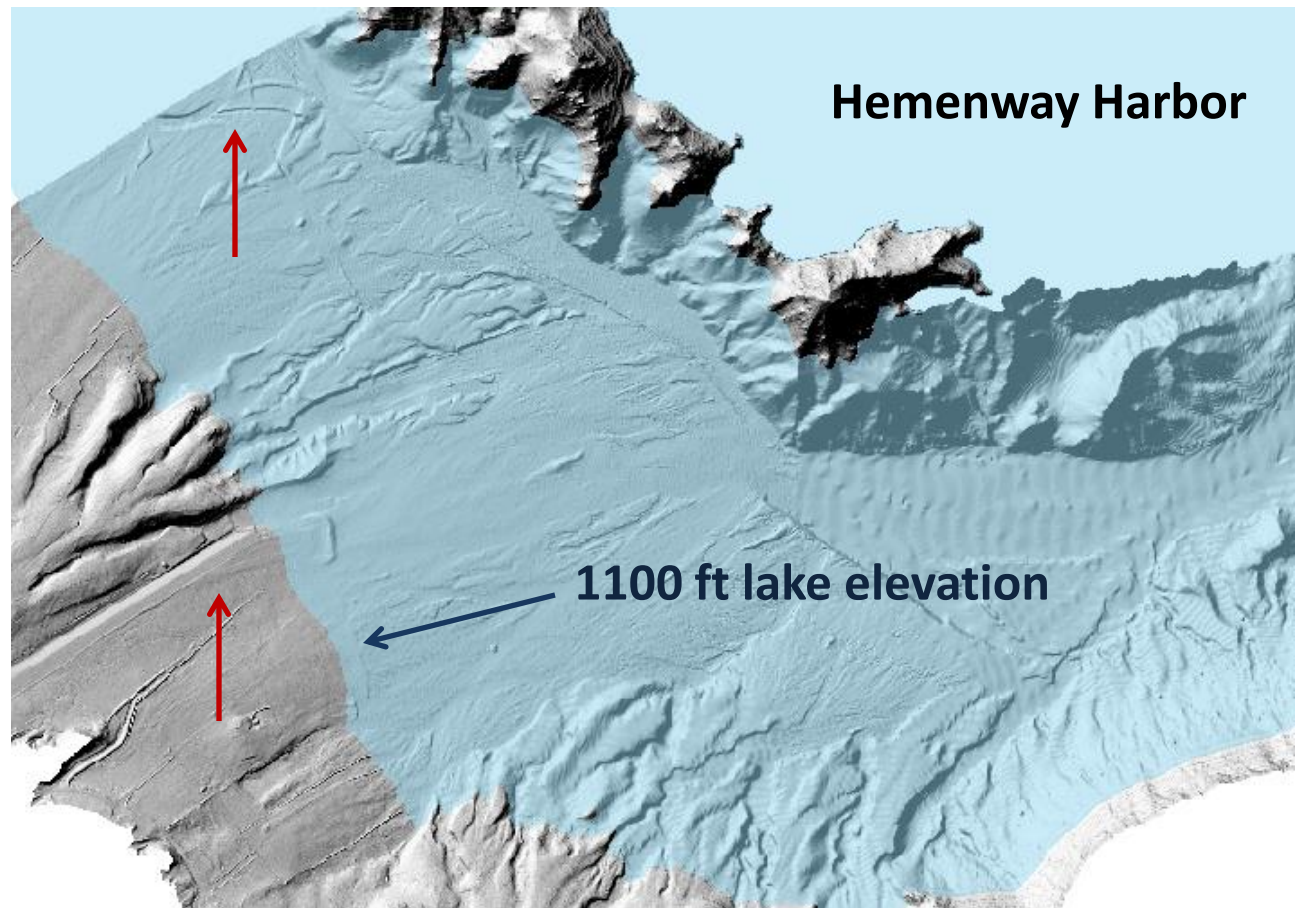
Multi-beam sonar



# High Resolution Bathymetric Mapping in Lake Mead

National Park Service  
2008 Marina Surveys

Multi-beam sonar





# High Resolution Bathymetric Mapping in Lake Mead

## National Park Service Ad-hoc surveys

### Single-beam sonar



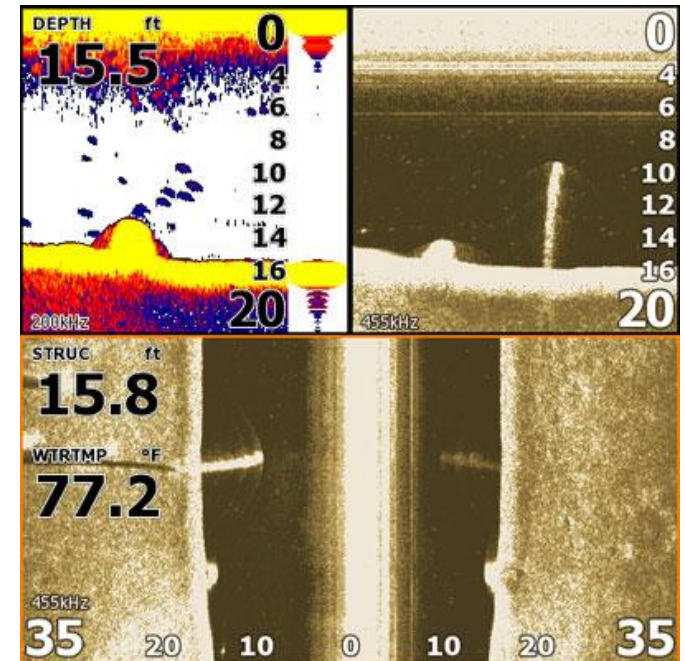
## Traditional Fish Finding Sonar

- Low cost
- Limited capability
- Limited detail and resolution
- No ability to record data and post-process



# Lowrance HDS Chartplotter (Generation 1)

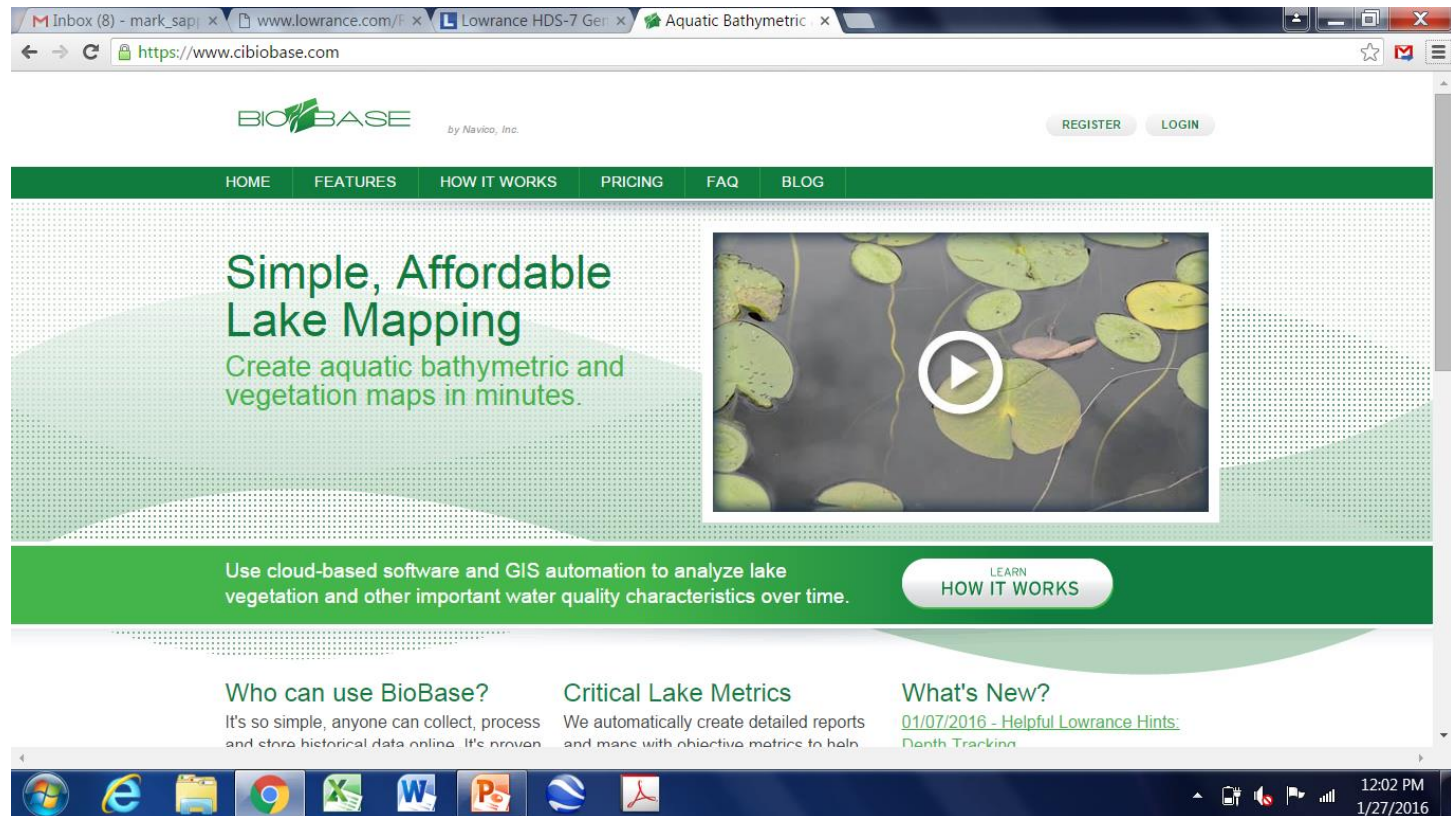
- Broadband sounder™
- StructureScan™
- 2 SD Cards: maps and data recording



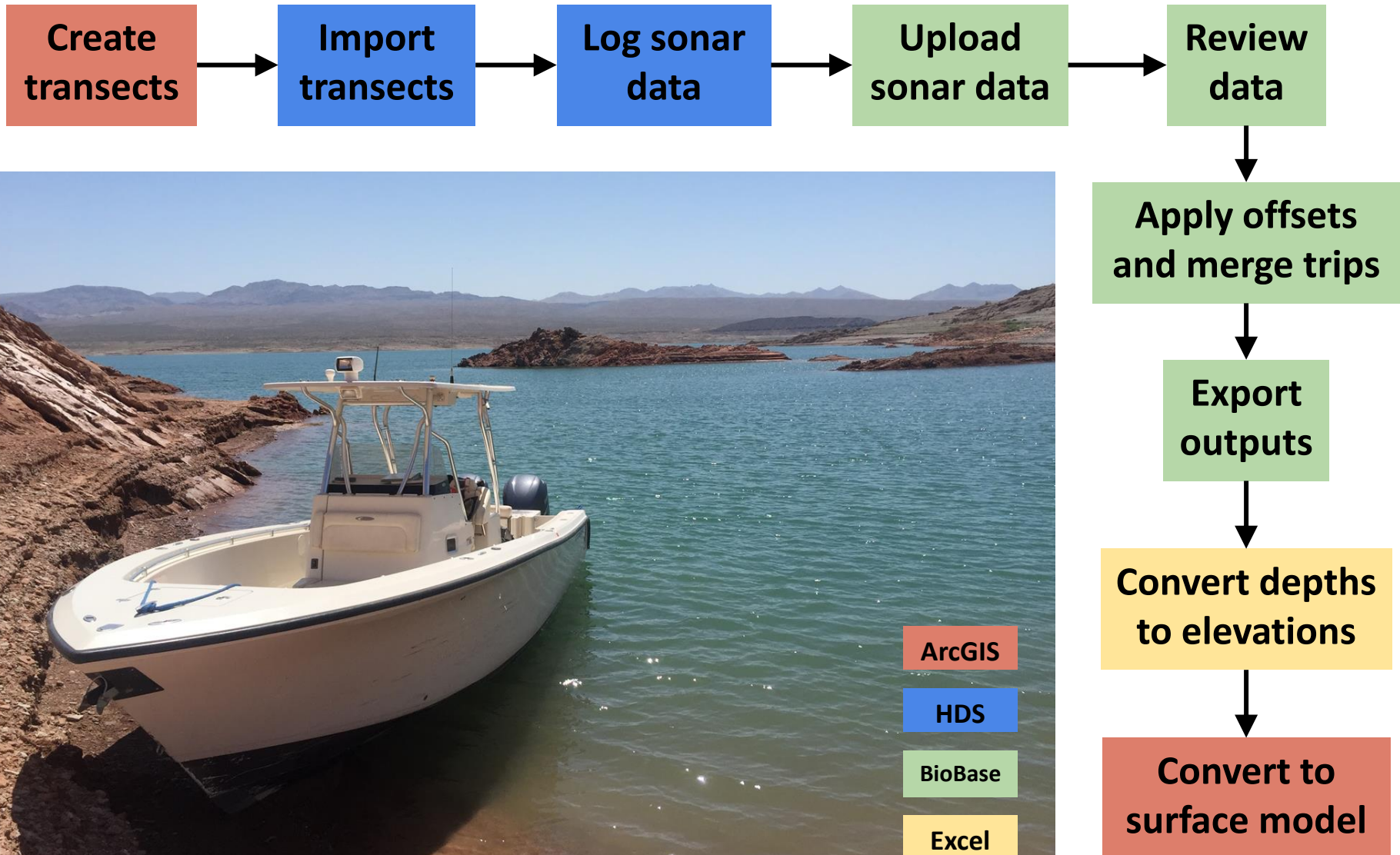


# BioBase Software Subscription Service

- Post-process sonar data from Lowrance HDS units
- High-resolution contour maps, vegetation maps, bottom hardness maps, change detection



# Overview of data collection and processing





# Creating Transects

- ArcMap 10.x
  - Create Fishnet Tool
    - Cell Size Width & Height = Transect Spacing
  - Remove undesired rows/columns
  - Optimize transect orientation, extent
  - Merge polylines into single line feature
  - Project to WGS84
- DNR GPS
  - Save shapefile/feature class as .gpx file

Area of Interest



20m Transects



# Logging Sonar Data

- Import transect .gpx to Lowrance chart plotter via SD card
- Chart plotter settings
  - Shallow water fishing mode
  - 10-15 pps ping rate
  - Auto sonar range
  - 200KHz frequency
  - WAAS differential correction enabled
- Recommended logging speed: 4 – 6 mph
- Log sonar (.sl2) in hourly blocks to SD card
  - Mitigate potential data loss
  - Account for changes in lake level

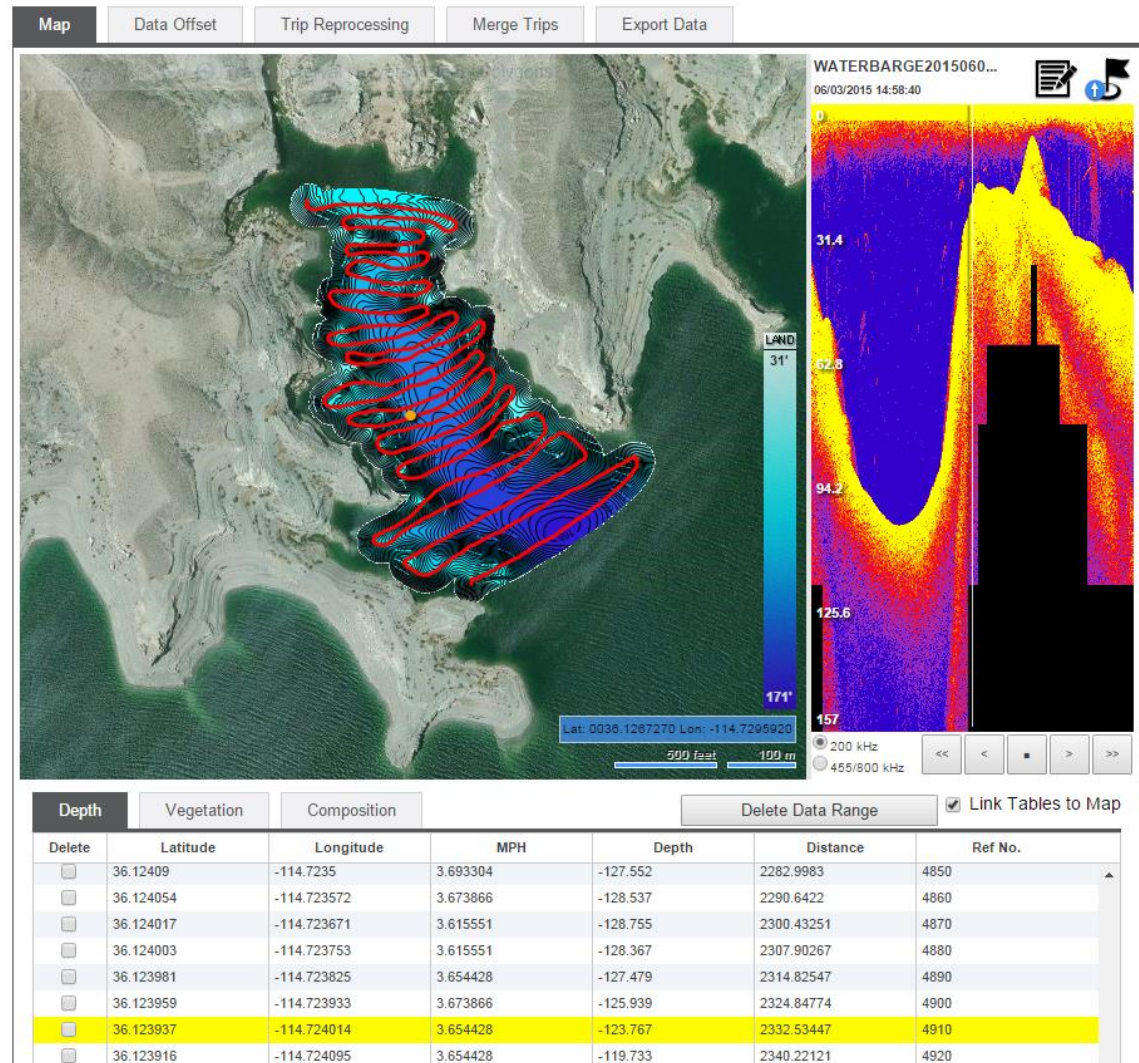


# Processing Sonar in BioBase

## Client Upload Tool



- Trip replay
- View tracklog, contours, vegetation, and composition
- Apply depth offsets
- Reprocess using appropriate track buffer
- Merge multiple trips into single file
- Export data to CSV file





# Quality Control

## From BioBase

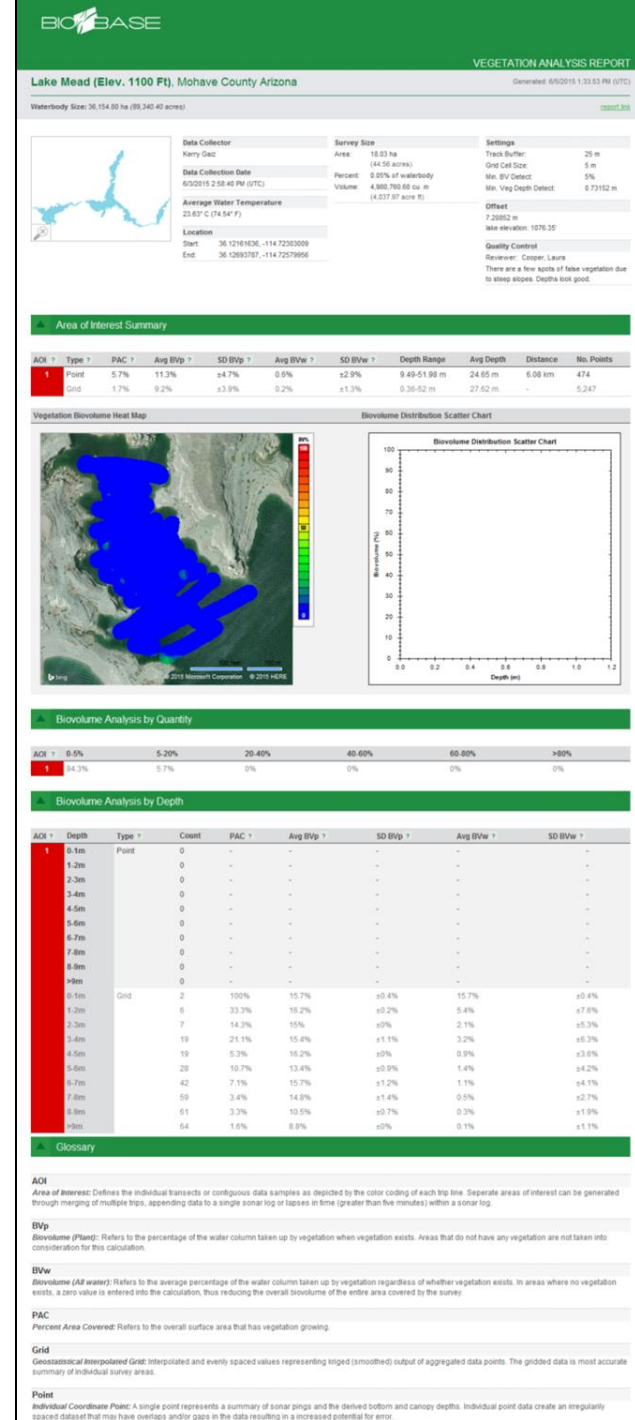
- Report within 24 hours that reviews:

- General trip info
- Vegetation
- Depth

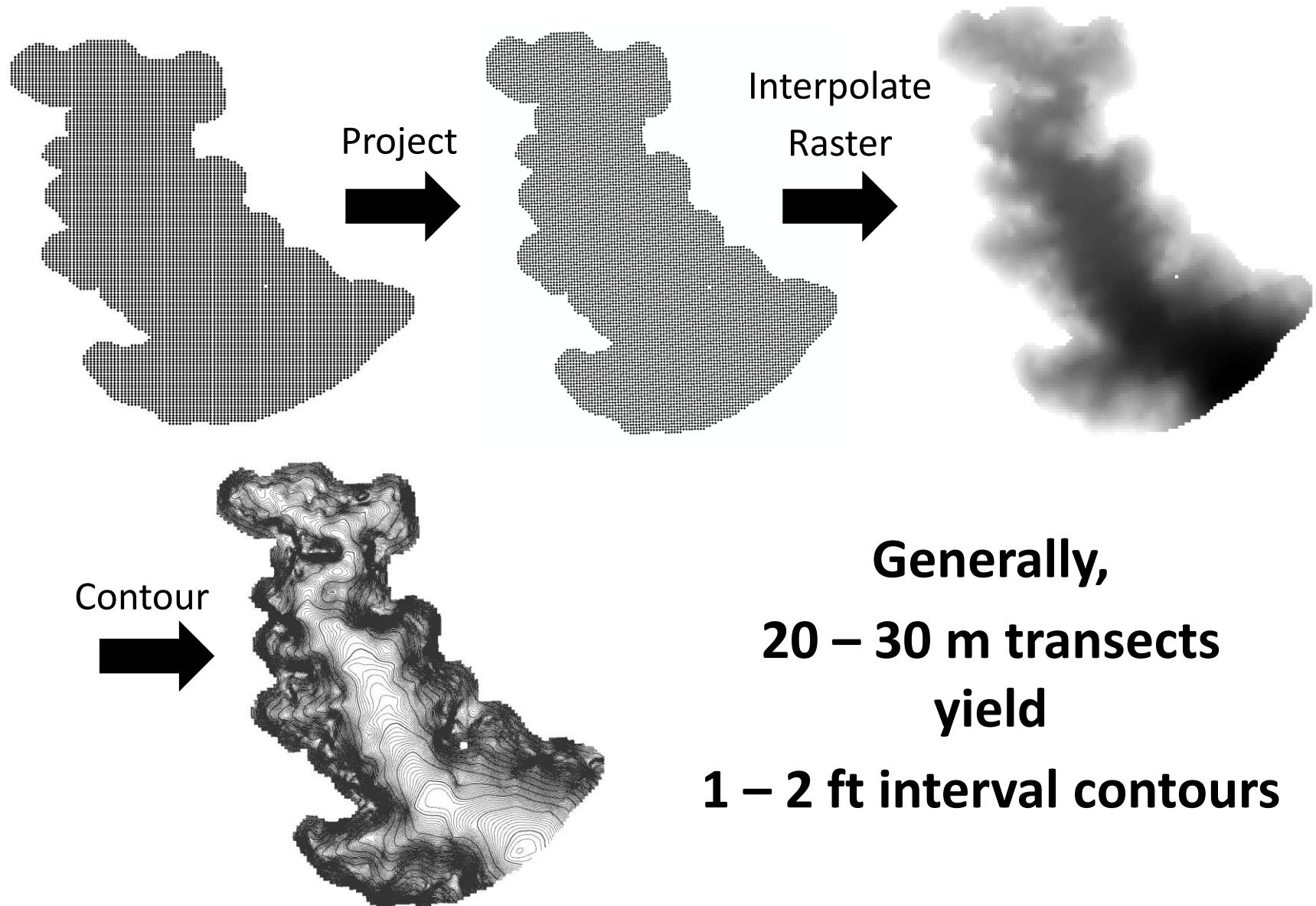
## In-house

- Review depth table
  - Remove erroneous depth readings

Depth	Vegetation	Composition	Delete Data Range				<input checked="" type="checkbox"/> Link Tables to Map
Delete	Latitude	Longitude	MPH	Depth	Distance	Ref No.	
<input type="checkbox"/>	36.125117	-114.723086	3.207343	-76.958	3118.49872	6660	
<input type="checkbox"/>	36.125095	-114.72314	3.285097	-81.491	3123.93398	6670	
<input type="checkbox"/>	36.125073	-114.723194	3.421166	-88.269	3129.36924	6680	
<input type="checkbox"/>	36.125044	-114.723248	3.654428	-95.695	3135.21197	6690	
<input type="checkbox"/>	36.12492	-114.723617	3.576674	-115.514	3142.68204	6740	
<input type="checkbox"/>	36.124898	-114.723698	3.732181	-117.715	3150.36868	6750	
<input type="checkbox"/>	36.124796	-114.723951	3.634989	-121.523	3158.71065	6780	



# Capabilities: bathymetric contours



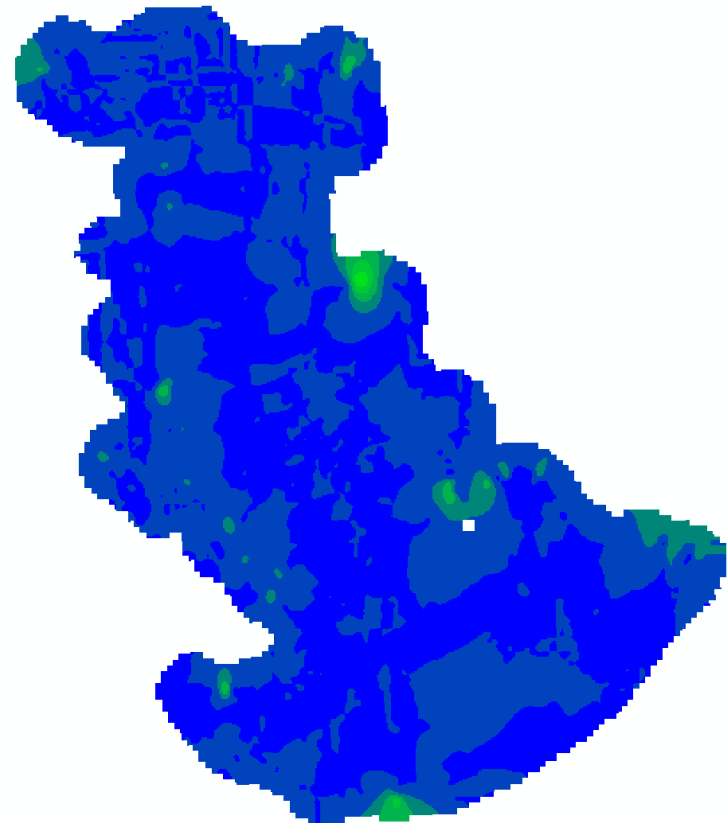
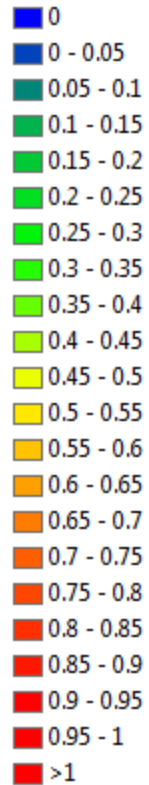
**Generally,  
20 – 30 m transects  
yield  
1 – 2 ft interval contours**

# Capabilities: aquatic vegetation maps

- Percent BioVolume 0 to 1

☐ ☒ Vegetation Percent BioVolume

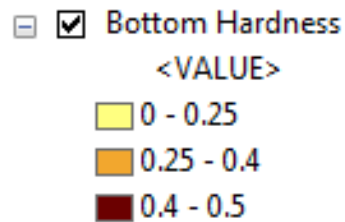
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# Capabilities: bottom composition maps

- 0 – 0.25 *Soft*
- 0.25 – 0.4 *Medium*
- 0.4 – 0.5 *Hard*



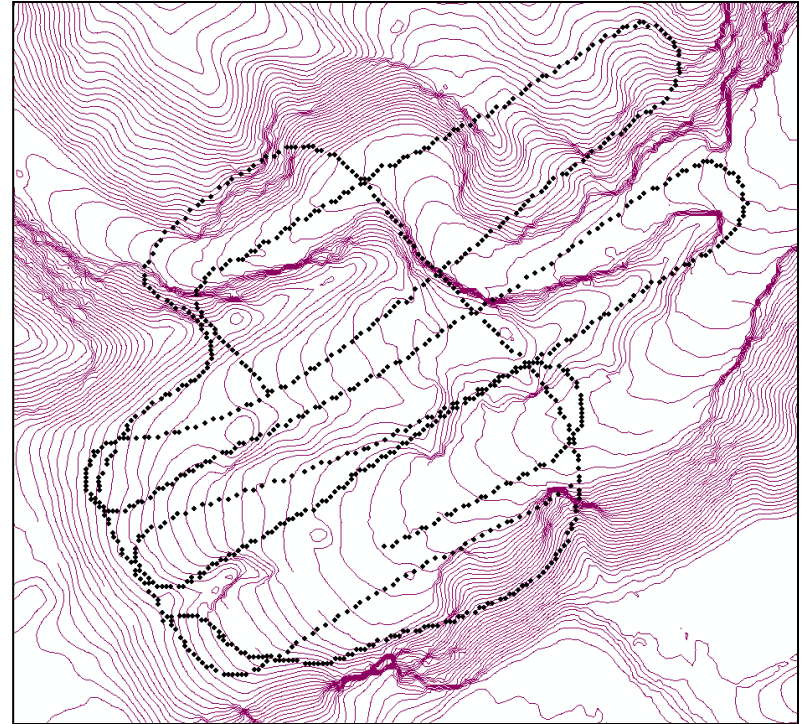
# Comparison to Survey Grade Data

Compared 1870 depth points  
recorded with Lowrance HDS  
at Temple Bar (2015)  
to 1 foot interval survey  
grade contours (2008)

## Result

Average Difference: 0.16 feet

Root Mean Square Error: 1.70 feet



## Lessons Learned

- Have not been accounting for transducer offset
- GPS lag on chart plotter
- Review file sizes on HDS before ending data collection
- Wave action affects accuracy

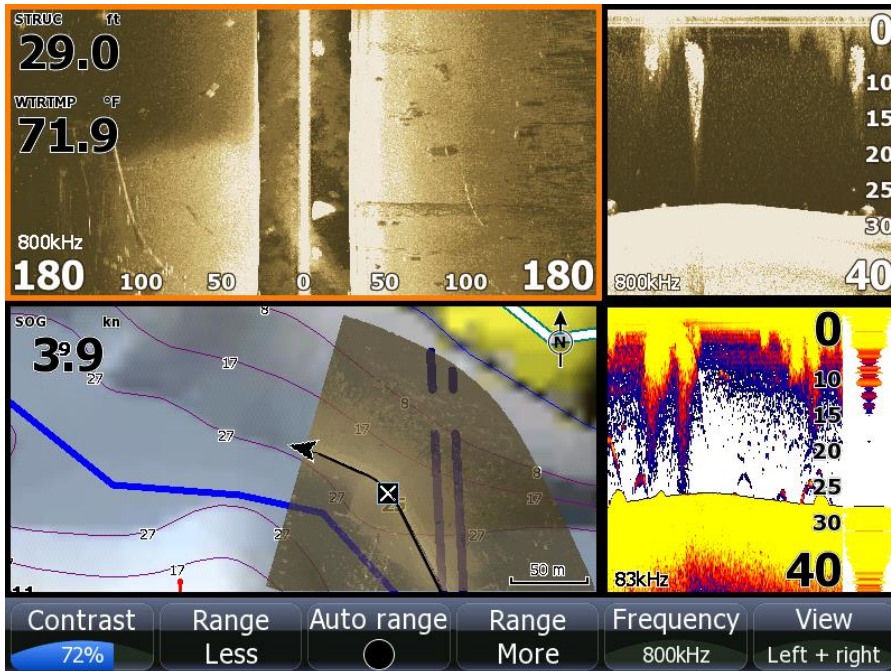


# Grant from National Parks Conservation Association to outfit a “survey boat”



# Lowrance HDS Chartplotter Generation 2

- Broadband sounder™
- StructureScan™
- StructureMap™



## Lowrance HDS Gen 2 System

- 9" HDS-9 Chartplotter
- Point-1 Precision GPS antenna
- M265 in-hull narrow beam transducer





# Lowrance Outboard Pilot™ Autopilot

- Hydraulic steering pump
- SmartSteer™ Autopilot computer





# Projects

## ***Planned:***

- *bathymetric mapping of Lake Mohave*

## ***Possible Future:***

- *mapping of substrate hardness relative to quagga mussel colonization densities*
- *underwater vegetation monitoring for invasive species*
- *change detection at Colorado River inflow after high flow events*

# Questions?



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